

Functional Data Analysis: Part I

Overview and Mean/Covariance Estimation

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Outline

- 1 Introduction
- 2 Mean and Covariance Estimation
- 3 Theory: Mean and Covariance Estimation

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What is Functional Data?

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 - These functions can be curves (1D), images (2D or 3D), or higher dimension object data.

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 - These functions can be curves (1D), images (2D or 3D), or higher dimension object data.
- Characteristics of functional data:
 - (i) The atom of functional data is a “function”.
 - (ii) They are ∞ -dimensional data.

Example: Curve Data

- **Curve data**

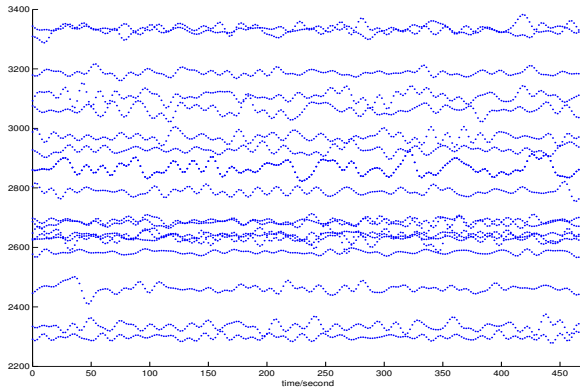
- real-valued functions defined on an interval $I \in \mathbb{R}$.
- one curve per subject

These curves are usually considered realizations of a stochastic process $X(t)$ in a **Hilbert space**, e.g.

$L^2(I)$ or RKHS (reproducing kernel Hilbert space).

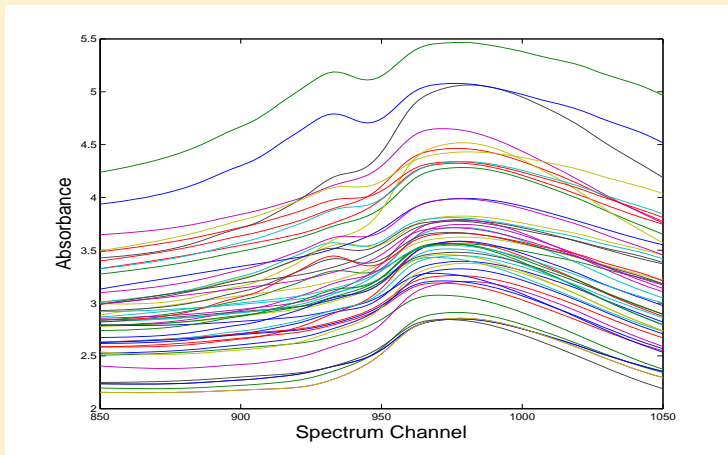
Examples of Functional Data

- fMRI data at a particular voxel for 20 subjects $\implies n = 20$.



Examples of Functional Data

- Spectrum data for meat content - here the function is over the spectrum channels of n pieces of meat.

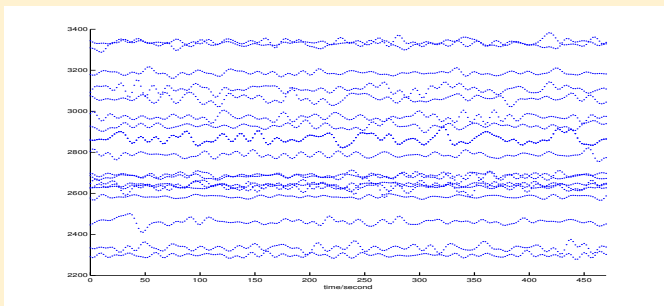


Additional Examples of Functional Data

- 10 minutes EKG recordings of 100 patients.
 $n = 100$
- Daily temperature recording in January at 240 locations.
 $n = 240$
- Daily reproduction (# of eggs) of 1000 female medflies (Mediterranean fruit flies) till death.
 $n = 1000$

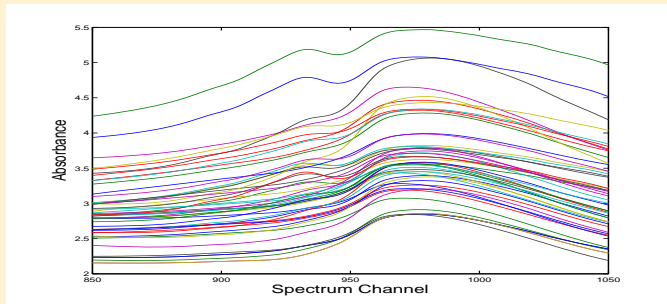
Real/Observed Functional Data

- In reality, functional data are recorded intensely on a time grid
⇒ high-dimensional data.
- * The fMRI data were recorded every two seconds for about 10 minutes (300 time points) ⇒ 300 dimensional data.



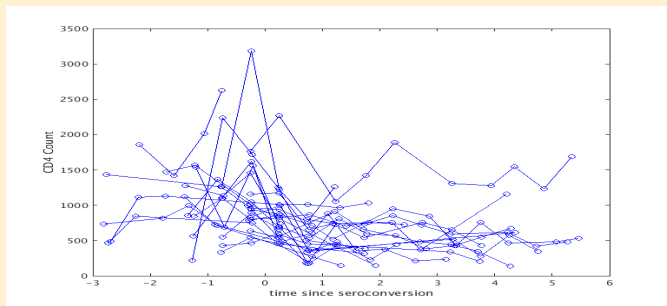
Real/Observed Functional Data

- The spectrum data were recorded at 100 frequency channels (hence 100-dim) and smoothed individually, i.e. **pre-smoothed**.



Longitudinal Data as Functional Data

- Longitudinal Data - Irregularly sampled functional data.
- They are often only a few measurements per subject, as in medical follow-up or social studies.



Longitudinal AIDS Data

- CD4 counts of 369 patients.

$n_i = \#$ of repeated measurements for subject i ,
varies with subject.

- An average of 6.44 measurement per subject.

Longitudinal AIDS Data

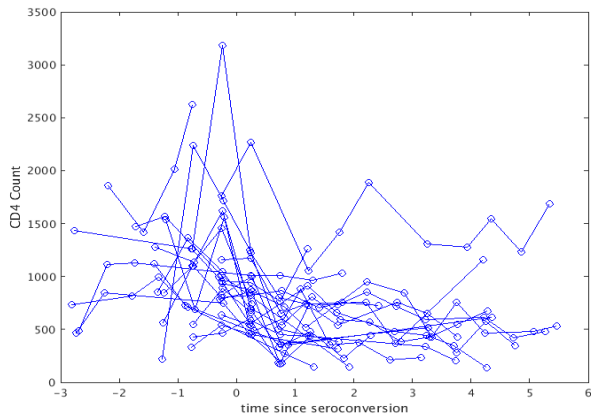
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- This results in longitudinal data with uneven $\#$ of measurements at irregular time-points.

CD4 Counts of First 25 Patients



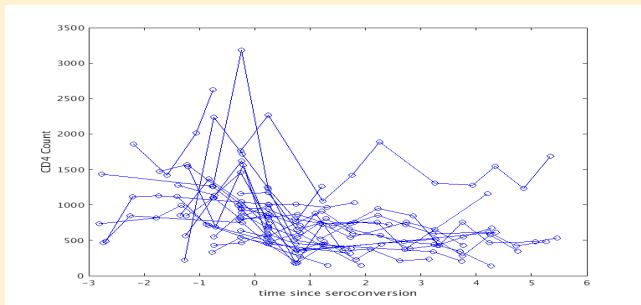
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 - Often smoothness of the functions is assumed.
- Longitudinal data have traditionally been modeled by a parametric approach, such as a linear mixed-effects model.
 - However, it may not be easy to spot the pattern due to sparsity of and noise in the longitudinal data.

Longitudinal vs Functional data



- This motivates a data oriented nonparametric approach, which luckily is feasible under mild design conditions.

Longitudinal vs Functional data

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⇒ the observed data for subject i might be

$$Y_{ij} = X_i(t_{ij}) + e_{ij}, \quad j = 1, \dots, n_i,$$

where $X_i(t)$ is a smooth random function,
 e_{ij} **are independent** $\forall i, j$.

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- A strength of the FDA approach is its ability to handle noise.

Summary

- There are the three types of functional data:
 - (i) stochastic processes $\implies \infty$ -dimensional data
 - (ii) intense/dense functional data \implies high dimensional data
 - (iii) sparse functional/longitudinal data \implies irregular dim. data.

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- The stochastic process $X_i(t)$ is assumed to be a continuous function.
(But the observed data may contain noise, a.k.a. measurement error.)
- Nonparametric approaches are typically employed to all three types of functional data.

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Answer: We borrow information by smoothing!

- We can do so because we have a natural ordering of the data.
- Chen, Chen, M. and W. (2011) proposed a way to reorder multivariate data and convert high-dim data to functional data.
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- The first implementation of functional principal component analysis (FPCA) were attributed to Rao (1958), where the growth data were recorded as multivariate data.
- The analysis of stochastic processes went even further back to Grenander (1950), Karhunen (1946), Loève (1946), and later include Kleffe (1973) and Dauxois and Poussé (1976).

History of FDA

- The handling of longitudinal data as sparse functional data was the focus in Yao et al. (2005), but nonparametric approaches for longitudinal data had already been employed by Shi et al. (1996), Staniswalis and Lee (1998), James et al. (2000), and Rice and Wu (2001).

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- Next generation functional data refer to functional data that are part of complex data objects, possibly multivariate, correlated, or involve images and shapes.
- Brain and neuroimaging data are examples of next generation functional data.

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- Review of FDA W., Chiou and Müller (2016)

End of Introduction



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Mean and Covariance Function

Data $\{X_1, \dots, X_n\}$ are i.i.d. copies of a random function $X(t)$:

- Mean function: $\mu(t) = E(X(t))$
- Covariance function: $\Sigma(s, t) = \text{cov}(X(s), X(t))$,
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where s & $t \in$ interval I .
- Regular functional data - All subjects are measured at the same time grid, t_1, \dots, t_m , often equally spaced \implies multivariate data.

Irregular functional data - The measurement schedule for subject i is $t_{i1}, \dots, t_{in_i} \implies$ longitudinal data.

Estimation of Mean and Covariance Functions: Dense and Regular Functional Data

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 - Such a mean estimate provides a \sqrt{n} -consistent (pointwise) estimate of the mean $\mu(t)$ even in the presence of measurement errors. (WHY?)
- The cross-section mean can further be smoothed slightly to obtain a smooth mean estimate (This requires a dense/intense measurement schedule).
 - **Think how you should smooth to retain the \sqrt{n} -consistent of the smooth estimate .**

Estimation of Mean and Covariance Functions: Dense and Regular Functional Data

- Likewise, the sample covariance matrix is also \sqrt{n} -consistent and can be slightly smoothed to retain the \sqrt{n} -rate of consistency.

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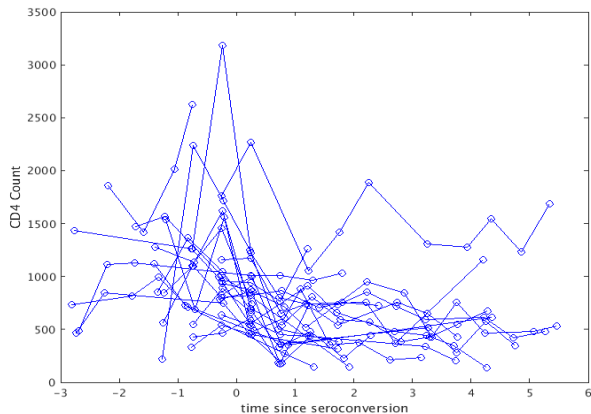
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 - The mean estimate could be \sqrt{n} -consistent (**pointwise**) for “**dense**” functional data but will have nonparametric rates otherwise.
(“Dense” functional data $\iff \sqrt{n}$ -rate of convergence is feasible.)

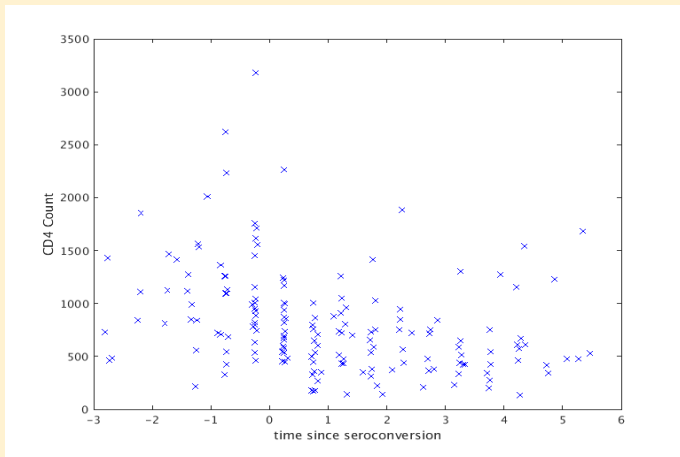
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(“Dense” functional data $\iff \sqrt{n}$ -rate of convergence is feasible.)
- Likewise, 2D smoothing is needed to estimate the covariance function. and \sqrt{n} -consistency can be achieved for **dense** functional data.

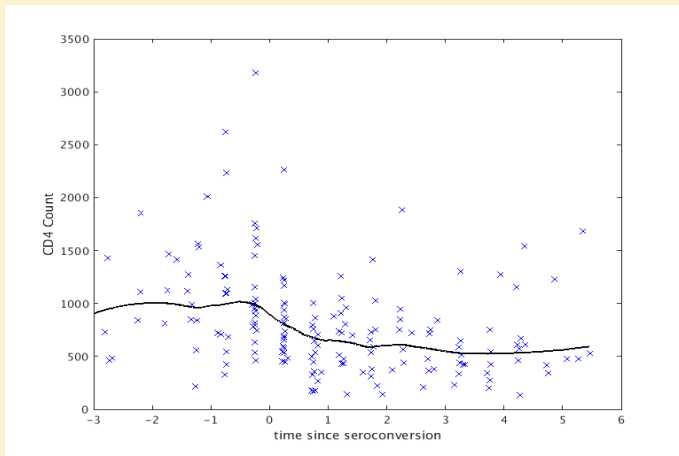
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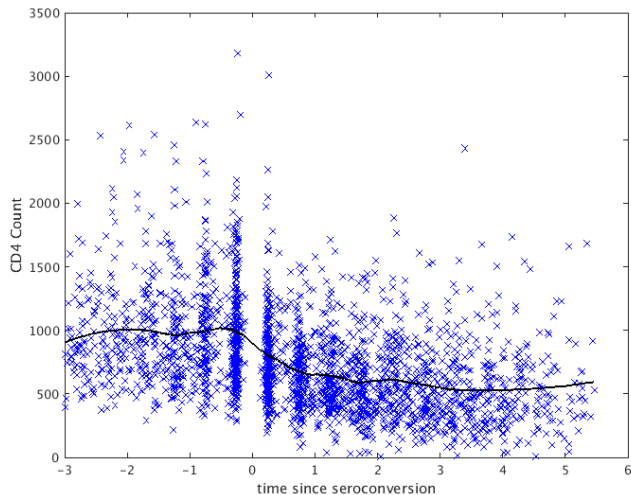
CD4 Counts of first 25 Patients



Mean Curve: CD4 Counts of first 25 Patients



Mean Curve: CD4 counts of all patients



Estimation of Mean Function

If we employ the local linear smoother, the estimate for the mean function is:

$$\hat{\mu}(t) = \hat{\beta}_0, \quad \text{where}$$
$$(\hat{\beta}_0, \hat{\beta}_1) = \underset{\beta_0, \beta_1}{\operatorname{argmin}} \quad \sum_{i=1}^n \sum_{j=1}^{n_i} \left[Y_{ij} - \beta_0 - \beta_1(T_{ij} - t) \right]^2 K_{h_\mu}(T_{ij} - t).$$

Remarks

- In addition to the local linear (or polynomial) smoother, any smoothing method, such as penalized splines, B-splines, Wavelets, and Fourier filtering, can be employed.

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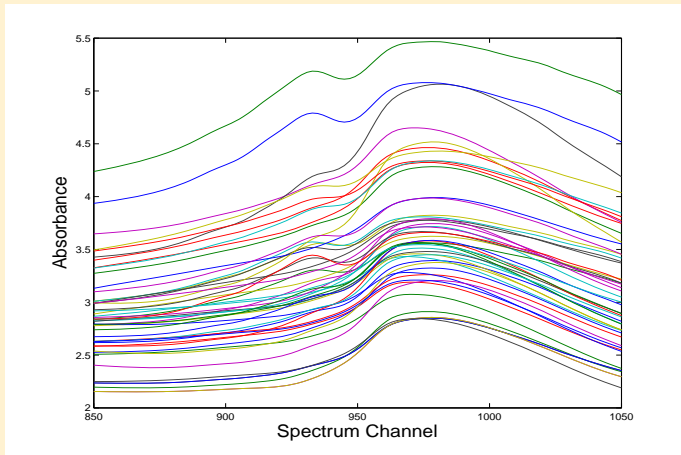
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- These smoothing methods (scatter plot smoothers) can also be applied to dense data, whether regular or not, so a unified approach is feasible.

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- In addition to the local linear (or polynomial) smoother, any smoothing method, such as penalized splines, B-splines, Wavelets, and Fourier filtering, can be employed.
- These smoothing methods (scatter plot smoothers) can also be applied to dense data, whether regular or not, so a unified approach is feasible.
- Another common approach for dense data is to pre-smooth the data from each subject separately, then take the cross-section mean at each time point t .

Remarks

This is the case for the spectrum data.



Remarks

- Such a pre-smoothing typically aims at:
 - (i) getting rid of the noise in the data,
 - (ii) revealing the latent smooth curve for each subject.
- Hall, M. W. (2006) and Zhang and Chen (2007).

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Hall, M. W. (2006) and Zhang and Chen (2007).
- However, both depend on the amount of smoothing and design of the dense data, so whether the mission has been accomplished is unclear.
- Because of this uncertainty and because pre-smoothing alters the data, we prefer not to adopt a pre-smoothing approach.

End of Estimation of Mean Function



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- Observe $Y_{ij} = Y_i(t_{ij}) = X_{ij} + e_{ij}$, where $\text{var}(e_{ij}) = \sigma^2(t_{ij})$.

$$\implies \text{cov}(Y(s), Y(t)) = \text{cov}(X(s), X(t)), \text{ when } s \neq t,$$

$$\text{var}(Y(t)) = \text{cov}(Y(t), Y(t)) = \text{cov}(X(t), X(t)) + \sigma^2(t).$$

Estimation of Covariance Function

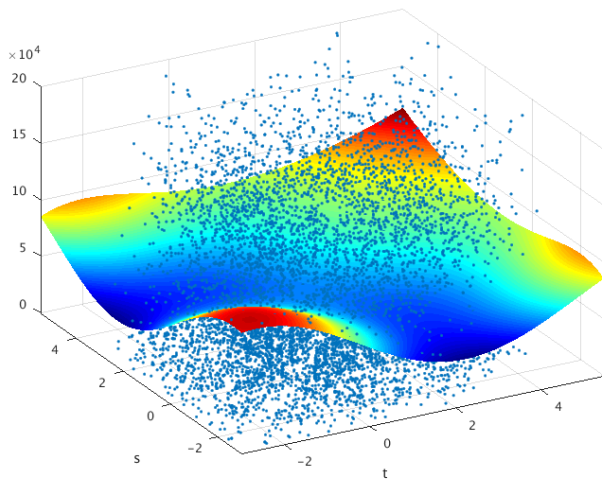
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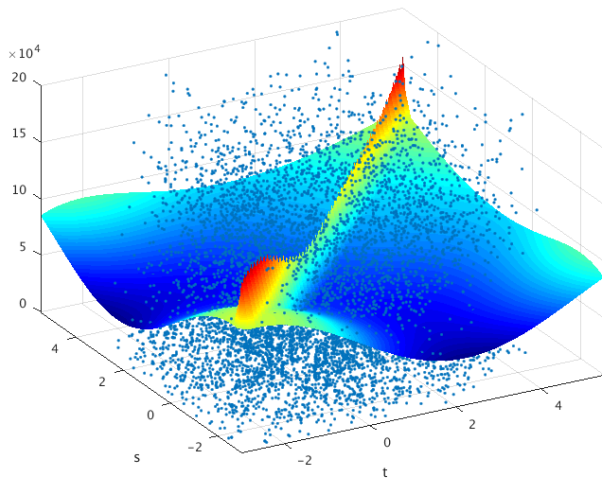
$$\text{var}(Y(t)) = \text{cov}(Y(t), Y(t)) = \text{cov}(X(t), X(t)) + \sigma^2(t).$$

- This means we need to handle the diagonal part of $\text{cov}(Y)$, which corresponds to the variance of Y , differently from the rest of $\text{cov}(Y)$.

Covariance Surface of $X(t)$

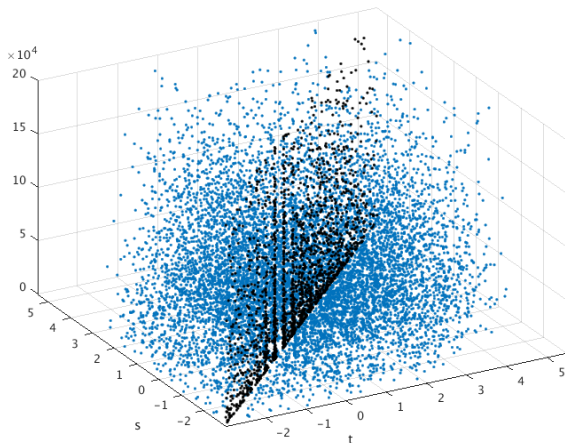


Covariance of $Y(t)$



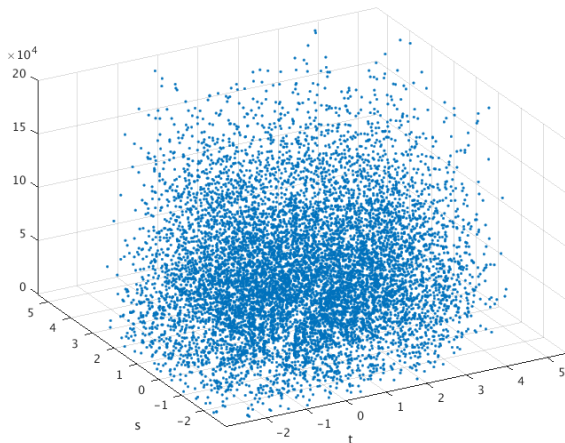
Raw Covariance Plot: Diagonal Data in Black

$$[Y(t_{ij}) - \hat{\mu}(t_{ij})][Y(t_{ik}) - \hat{\mu}(t_{ik})], \quad \forall i, j, k$$

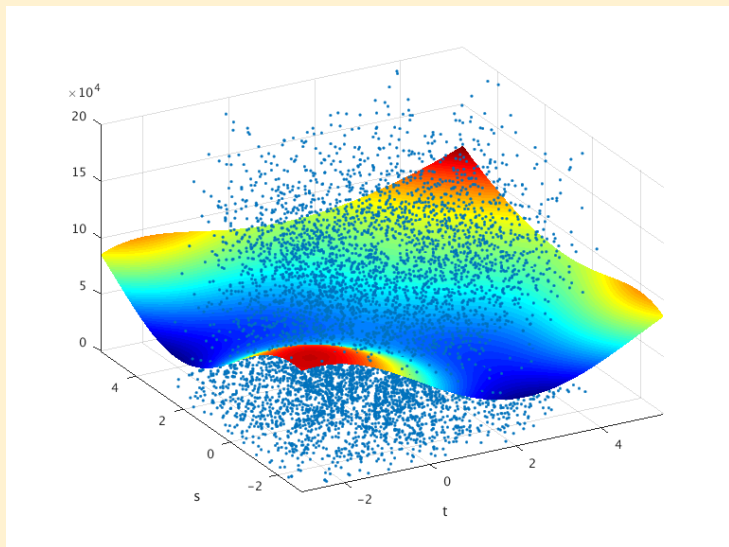


Raw Covariance with Diagonal Data Removed

$$[Y(t_{ij}) - \hat{\mu}(t_{ij})][Y(t_{ik}) - \hat{\mu}(t_{ik})], \quad \forall i, j \neq k$$

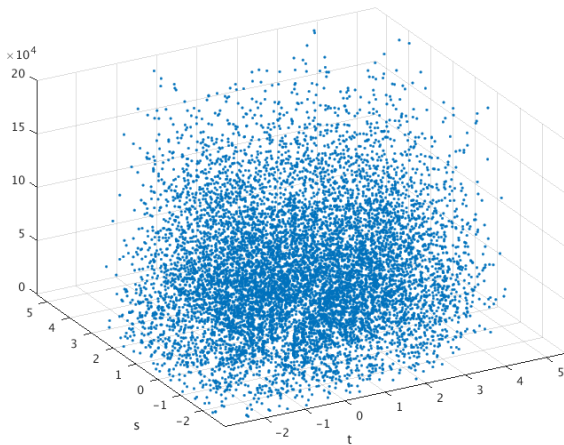


2D Smoother to Estimate the Covariance of $X(t)$

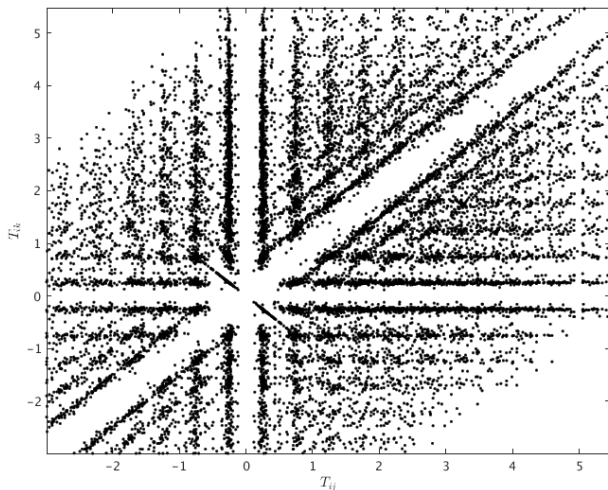


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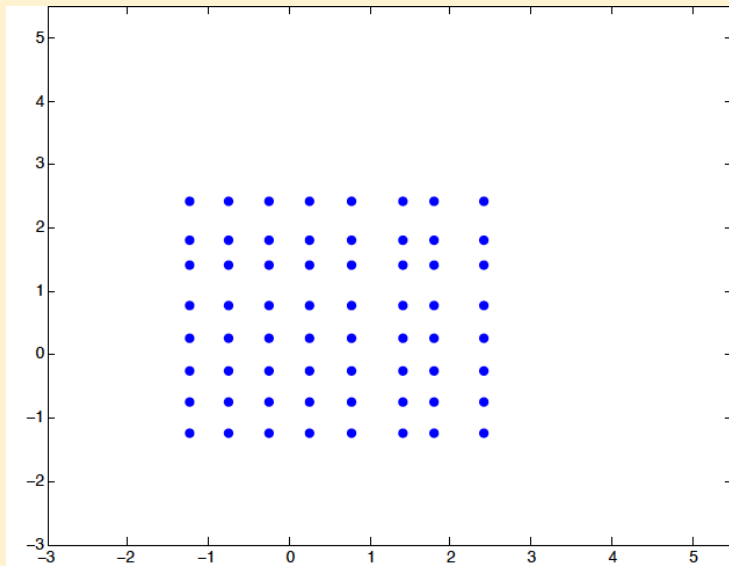
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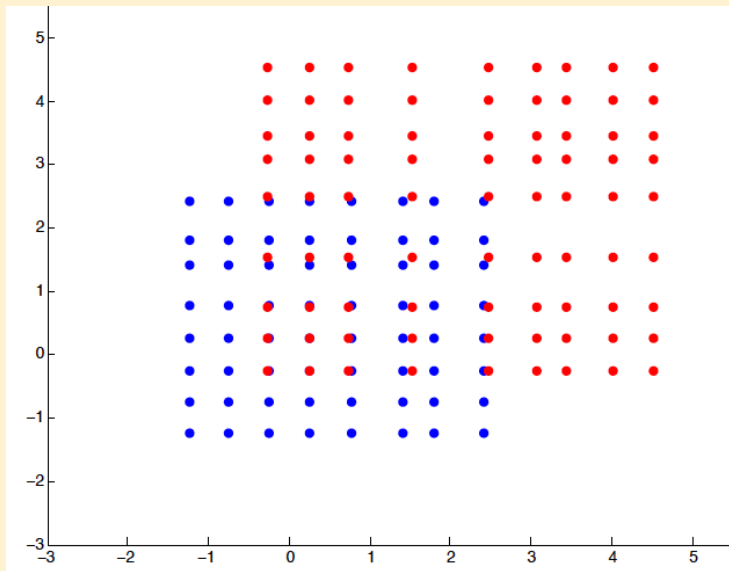
Design Plot for Covariance: $(t_{ij}, t_{ik}), \forall i, j \neq k$



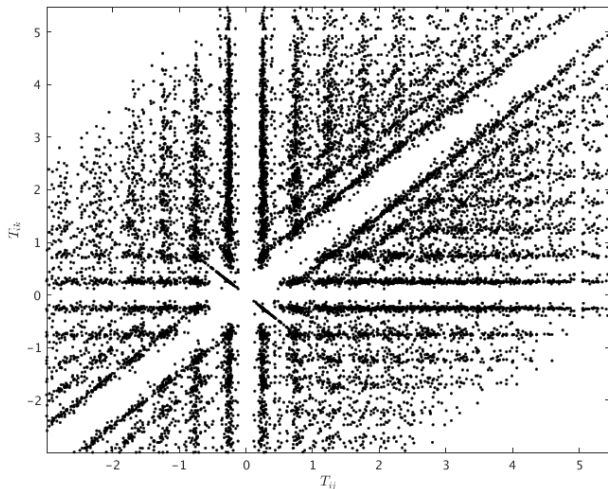
Design Plot for One Subject: $(t_{ij}, t_{ik}), \forall j, k$



Design Plot for Two Subjects: $(t_{ij}, t_{ik}), \forall j, k$



Design Plot for All Subjects: $(t_{ij}, t_{ik}), \forall i, j, k$



Estimated Covariance Surface of $X(t)$

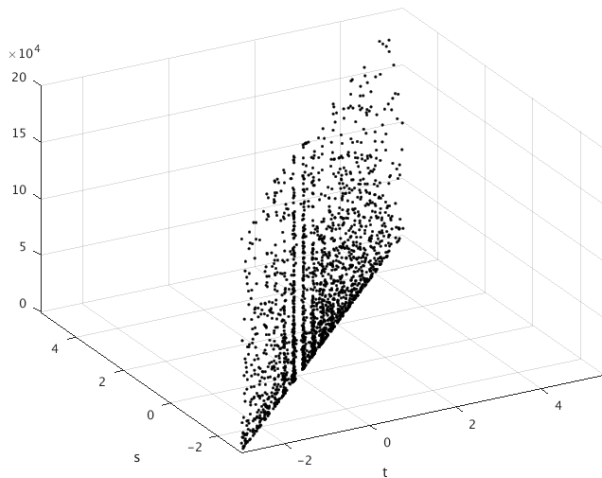
Let $D_{ijl} = (Y_{ij} - \hat{\mu}(t_{ij}))(Y_{il} - \hat{\mu}(t_{il}))$, be the raw covariances.

Employing a local linear smoother, the estimate for $\Sigma(s, t)$ is:

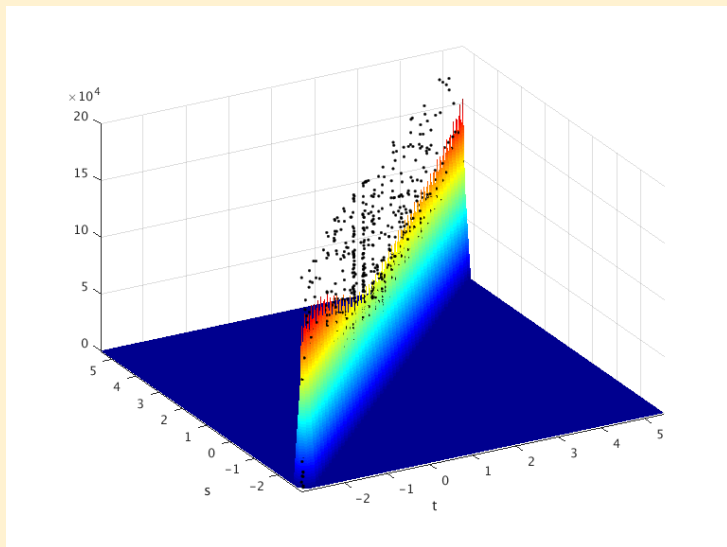
$\hat{\Sigma}(s, t) = \hat{\beta}_0$, where

$$(\hat{\beta}_0, \hat{\beta}_1, \hat{\beta}_2) = \underset{\beta_0, \beta_1, \beta_2}{\operatorname{argmin}} \sum_{i=1}^n \sum_{1 \leq j \neq l \leq n_i} \left[D_{ijl} - \beta_0 - \beta_1(t_{ij} - s) - \beta_2(t_{il} - t) \right]^2 K_{h_\Sigma}(t_{ij} - s) K_{h_\Sigma}(t_{il} - t).$$

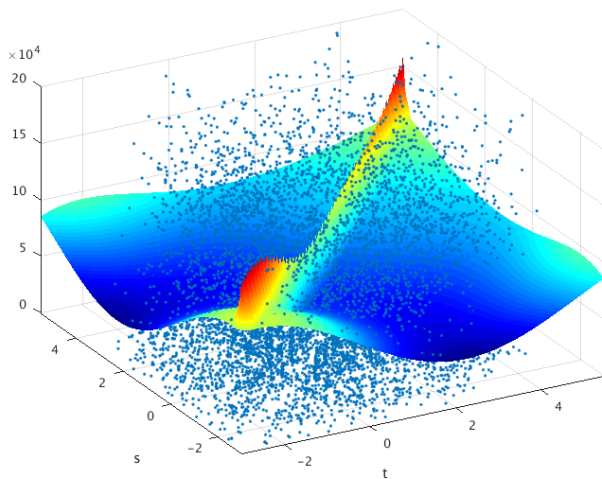
Raw Variance Plot: $[Y(t_{ij}) - \mu(t_{ij})]^2, \forall i, j$



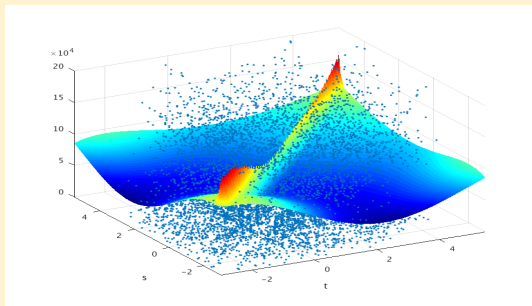
Estimated Variance function of $Y(t)$



Estimated Covariance & Variance of $Y(t)$

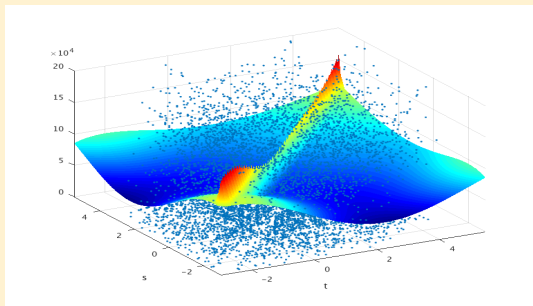


Estimates of $\sigma^2(t)$: Variance of Measurement Errors



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$$\sigma^2(t) = \text{var}(Y(t)) - \text{var}(X(t)).$$

When $\sigma^2(t) = \sigma^2$ for all t , one can estimate σ^2 by $\int_I \hat{\sigma}^2(t) dt$.

Due to boundary effects, PACE replaces I by a sub-interval.

PACE (Matlab) Package for FDA:

<http://www.stat.ucdavis.edu/PACE/>



fdapace: R-package of PACE

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 - But it only contains a few core functions in PACE.
- fdapace is still under construction - Feedback welcome!

End of Covariance Estimation



Outline

- 1 Introduction
- 2 Mean and Covariance Estimation
- 3 Theory: Mean and Covariance Estimation

Theory: Mean and Covariance Estimation

(Zhang and W., 2016)

- So far, we have used “**scatter plot smoothers**” to estimate the mean and covariance functions.

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 - It works for any type of sampling plan: regular, dense, or not.
 - It assigns the same weight to each observation, so a subject with more measurements (large n_i) receives a larger total weight.
- Another way to assign weights is to give equal weights, $\frac{1}{n}$, to all subjects as proposed in Li and Hsing (2010).

Theory: Mean and Covariance Estimation

(Zhang and W., 2016)

- Which weight assignment is better?

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- **Which weight assignment is better?**
- In Zhang and W. (2016) we present asymptotic properties of these estimators and define what “dense” functional data means.
- A referee requested that we develop a general theory using a general weight function, which covers both weighing schemes.
- As a result, an optimal weighing scheme based on convex combinations of the two weights was developed.

Estimation of Mean Function

- Equal weight per observation (Yao, Müller and W., 2005)

$\hat{\mu}_{obs}(t) = \hat{\beta}_0$ where

$$(\hat{\beta}_0, \hat{\beta}_1) = \underset{\beta_0, \beta_1}{\operatorname{argmin}} \sum_{i=1}^n \sum_{j=1}^{n_i} \left[Y_{ij} - \beta_0 - \beta_1(T_{ij} - t) \right]^2 K_{h_\mu}(T_{ij} - t).$$

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- Equal weight per subject (Li and Hsing, 2010)

$\hat{\mu}_{sub}(t) = \hat{\beta}_0$ where

$$(\hat{\beta}_0, \hat{\beta}_1) = \underset{\beta_0, \beta_1}{\operatorname{argmin}} \sum_{i=1}^n \frac{1}{\mathbf{n}_i} \sum_{j=1}^{n_i} \left[Y_{ij} - \beta_0 - \beta_1(T_{ij} - t) \right]^2 K_{h_\mu}(T_{ij} - t).$$

Estimation of Mean Function

- A general weighing scheme (Zhang and W., 2016),
 - weight \mathbf{w}_i for subject i , where $\sum_{i=1}^n n_i w_i = 1$.

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- The OBS scheme uses $w_i = \frac{1}{\sum_{i=1}^n n_i} \Rightarrow$ the same for all subjects.
The SUBJ scheme uses $w_i = \frac{1}{nn_i}$.

Important notation

n = Sample size, n_i = # observations of subject i .

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$$\bar{N} = \frac{1}{n} \sum_{i=1}^n n_i, \quad \bar{N}_{S2} = \frac{1}{n} \sum_{i=1}^n n_i^2.$$

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- SUB: harmonic mean of n_i ,

$$\bar{N}_H = \frac{n}{\sum_{i=1}^n \frac{1}{n_i}}, \quad \frac{\bar{N}_{S2}}{(\bar{N})^2} \rightarrow 1.$$

Asymptotic Normality

- OBS:

$$[\Gamma_{obs}(t)]^{-1/2} \left\{ \hat{\mu}_{obs}(t) - \mu(t) - \underbrace{\frac{1}{2} h_{\mu}^2 \sigma_K^2 \mu^{(2)}(t)}_{\text{asymptotic bias}} \right\} \xrightarrow{d} \mathcal{N}(0, 1), \quad \text{where}$$

$$\underbrace{\Gamma_{obs}(t)}_{\text{asymptotic variance}} = \|K\|^2 \frac{\Sigma(t, t) + \sigma^2}{n \bar{N} h_{\mu} f(t)} + \frac{(\bar{N}_{S2} - \bar{N})}{n(\bar{N})^2} \Sigma(t, t).$$

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- SUB

$$[\Gamma_{sub}(t)]^{-1/2} \left\{ \hat{\mu}_{sub}(t) - \mu(t) - \underbrace{\frac{1}{2} h_{\mu}^2 \sigma_K^2 \mu^{(2)}(t)}_{\text{asymptotic bias}} \right\} \xrightarrow{d} \mathcal{N}(0, 1), \quad \text{where}$$

$$\underbrace{\Gamma_{sub}(t)}_{\text{asymptotic variance}} = \|K\|^2 \frac{\Sigma(t, t) + \sigma^2}{n \bar{N}_H h_{\mu} f(t)} + \frac{1}{n} \left(1 - \frac{1}{\bar{N}_H} \right) \Sigma(t, t)$$

Rates of Convergence

- ① Non-dense: Slower than \sqrt{n} -rate.
Sparse data = finite n_i , is a special case.

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Sparse data = finite n_i , is a special case.
- ② Dense: \sqrt{n} -rate, with asymptotic bias
(between non- and parametric paradigm)
- ③ Ultra-dense: \sqrt{n} -rate, no asymptotic bias
(Parametric paradigm)

Partition of Functional Data: OBS

Assume $\limsup_n (\bar{N}_{S2})/(\bar{N})^2 < \infty$.

❶ **Non-Dense data:** When $\bar{N}/n^{1/4} \rightarrow 0$ and $h_\mu \asymp (n\bar{N})^{-1/5}$,

$$\sqrt{n\bar{N}h_\mu} [\hat{\mu}_{obs}(t) - \mu(t) - \frac{1}{2}h_\mu^2\sigma_K^2\mu^{(2)}(t)] \xrightarrow{d} \mathcal{N}\left(0, \|K\|^2 \frac{\Sigma(t,t) + \sigma^2}{f(t)}\right).$$

❷ **Dense data:** When $\bar{N}/n^{1/4} \rightarrow C$ and $h_\mu/n^{-1/4} \rightarrow C_1$ where $0 < C, C_1 < \infty$,

$$\sqrt{n \frac{(\bar{N})^2}{\bar{N}_{S2}}} [\hat{\mu}_{obs}(t) - \mu(t) - \frac{1}{2}h_\mu^2\sigma_K^2\mu^{(2)}(t)] \xrightarrow{d} \mathcal{N}\left(0, \|K\|^2 \frac{\Sigma(t,t) + \sigma^2}{f(t) \cdot C_1} + \Sigma(t,t)\right).$$

❸ **Ultra-Dense data:** When $\bar{N}/n^{1/4} \rightarrow \infty$, $h_\mu = o(n^{-1/4})$, and $h_\mu\bar{N} \rightarrow \infty$,

$$\sqrt{n \frac{(\bar{N})^2}{\bar{N}_{S2}}} [\hat{\mu}_{obs}(t) - \mu(t)] \xrightarrow{d} \mathcal{N}(0, \Sigma(t,t)).$$

Partition of Functional Data: SUB

- ❶ **Non-Dense data:** When $\bar{N}_H/n^{1/4} \rightarrow 0$ and $h_\mu \asymp (n\bar{N}_H)^{-1/5}$,

$$\sqrt{n\bar{N}_H h_\mu} [\hat{\mu}_{sub}(t) - \mu(t) - \frac{1}{2} h_\mu^2 \sigma_K^2 \mu^{(2)}(t)] \xrightarrow{d} \mathcal{N} \left(0, \|K\|^2 \frac{\Sigma(t, t) + \sigma^2}{f(t)} \right).$$

- ❷ **Dense data:** When $\bar{N}_H/n^{1/4} \rightarrow C$ and $h_\mu/n^{-1/4} \rightarrow C_1$ where $0 < C, C_1 < \infty$,

$$\sqrt{n} [\hat{\mu}_{sub}(t) - \mu(t) - \frac{1}{2} h_\mu^2 \sigma_K^2 \mu^{(2)}(t)] \xrightarrow{d} N \left(0, \|K\|^2 \frac{\Sigma(t, t) + \sigma^2}{f(t)C \cdot C_1} + \Sigma(t, t) \right).$$

- ❸ **Ultra-Dense data:** When $\bar{N}_H/n^{1/4} \rightarrow \infty$, $h_\mu = o(n^{-1/4})$, and $h_\mu \bar{N}_H \rightarrow \infty$,

$$\sqrt{n} [\hat{\mu}_{sub}(t) - \mu(t)] \xrightarrow{d} \mathcal{N}(0, \Sigma(t, t)).$$

- This shows $\hat{\mu}_{sub}(t)$ is asymptotically equivalent to the sample mean when the true curves $X_i(t)$ can be observed without any measurement errors.

Comparison of Two Schemes

① **Asymptotic bias:** both $= \frac{1}{2}h_{\mu}^2\sigma_K^2\mu^{(2)}(t)$.

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① **Asymptotic bias:** both $= \frac{1}{2}h_{\mu}^2\sigma_K^2\mu^{(2)}(t)$.

② **Asymptotic variance:**

- **Non-dense data:** $\text{var}(\hat{\mu}_{obs}) \leq \text{var}(\hat{\mu}_{sub})$, so OBS is more efficient.
- **Ultra-dense data:** $\text{var}(\hat{\mu}_{obs}) \geq \text{var}(\hat{\mu}_{sub})$, so SUB is more efficient.

L^2 Convergence

- Equal weight per observation:

$$\|\hat{\mu}_{obs} - \mu\|_2 = O_p \left(h_\mu^2 + \sqrt{\left(\frac{\bar{N} S_2}{(\bar{N})^2} + \frac{1}{\bar{N} h_\mu} \right) \frac{1}{n}} \right).$$

- Equal weight per subject:

$$\|\hat{\mu}_{sub} - \mu\|_2 = O_p \left(h_\mu^2 + \sqrt{\left(1 + \frac{1}{\bar{N}_H h_\mu} \right) \frac{1}{n}} \right)$$

Uniform Convergence

- Equal weight per observation:

$$\sup_{t \in [0,1]} |\hat{\mu}_{obs}(t) - \mu(t)| = O \left(h_{\mu}^2 + \sqrt{\left(\frac{\bar{N}_{S2}}{(\bar{N})^2} + \frac{1}{\bar{N}h_{\mu}} \right) \frac{\log(n)}{n}} \right) \quad a.s.$$

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Optimal Weighing Scheme

- Optimal weights for a convex combination of the two estimators exists.

$$w_i = \alpha \frac{1}{n\bar{N}} + (1 - \alpha) \frac{1}{nN_i}$$

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- Optimal weights:

$$\alpha^* = \frac{c_{n2}}{c_{n1} + c_{n2}},$$

where c_{n1} and c_{n2} are respectively the asymptotic variance of $\hat{\mu}_{obj}$ and $\hat{\mu}_{sub}$.

Optimal Weighing Scheme

- Let $\hat{\mu}_{\alpha^*}$ be the estimate with the optimal weights,
 $w_i = \alpha^* \frac{1}{nN} + (1 - \alpha^*) \frac{1}{nN_i}.$

$$\Rightarrow \|\hat{\mu}_{\alpha^*} - \mu\|_2 = O_p \left(h_{\mu}^2 + \sqrt{\frac{c_{n1}c_{n2}}{c_{n1}+c_{n2}}} \right).$$

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- Since $\frac{c_{n1}c_{n2}}{c_{n1}+c_{n2}} \leq \min\{c_{n1}, c_{n2}\}$, the rate for $\hat{\mu}_{\alpha^*}$ is always at least as good as those for $\hat{\mu}_{obj}$ and $\hat{\mu}_{sub}$.

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- Simulation results in Zhang and W. (2016) show superior performance of $\hat{\mu}_{\alpha^*}$.

End of Theory for Mean Function



Covariance Estimate with General Weights

- Let $D_{ijl} = (Y_{ij} - \hat{\mu}(T_{ij}))(Y_{il} - \hat{\mu}(T_{il}))$ be the raw covariance based on a mean estimate $\hat{\mu}$.
- Let \mathbf{v}_i be the weight attached to each observation for the i th subject with $\sum_{i=1}^n n_i(n_i - 1)\mathbf{v}_i = 1$.

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- Let \mathbf{v}_i be the weight attached to each observation for the i th subject with $\sum_{i=1}^n n_i(n_i - 1)\mathbf{v}_i = 1$.
- A general covariance estimator based on the weights \mathbf{v}_i is:
 $\hat{\Sigma}(s, t) = \hat{\beta}_0$, where

$$(\hat{\beta}_0, \hat{\beta}_1, \hat{\beta}_2) = \underset{\beta_0, \beta_1, \beta_2}{\operatorname{argmin}} \sum_{i=1}^n \mathbf{v}_i \sum_{1 \leq j \neq l \leq n_i} \left[D_{ijl} - \beta_0 - \beta_1(T_{ij} - s) - \beta_2(T_{il} - t) \right]^2 K_{h_\Sigma}(T_{ij} - s) K_{h_\Sigma}(T_{il} - t)$$

Covariance Estimators: Two Special Cases

- ① $D_{ijl} = (Y_{ij} - \hat{\mu}_{obs}(T_{ij}))(Y_{il} - \hat{\mu}_{obs}(T_{il}))$ and $\mathbf{v_i} = \frac{1}{\sum_{i=1}^n n_i(n_i-1)}$
 \implies OBS scheme.
- ② $D_{ijl} = (Y_{ij} - \hat{\mu}_{sub}(T_{ij}))(Y_{il} - \hat{\mu}_{sub}(T_{il}))$ and $v_i = 1/(n_i(n_i - 1))$
 \implies SUB scheme.

Asymptotic Normality

Let

$$V_1(s, t) = \text{Var}[(Y_1 - \mu(T_1))(Y_2 - \mu(T_2)) \mid T_1 = s, T_2 = t];$$

$$V_2(s, t) = \text{Cov}([Y_1 - \mu(T_1)][Y_2 - \mu(T_2)], [Y_1 - \mu(T_1)][Y_3 - \mu(T_3)] \mid T_1 = s, T_2 = t, T_3$$

$$V_3(s, t) = \text{Cov}([Y_1 - \mu(T_1)][Y_2 - \mu(T_2)], [Y_3 - \mu(T_3)][Y_4 - \mu(T_4)] \mid T_1 = s, T_2 = t, T_3$$

$$\Gamma_\gamma^{-1/2} \left[\hat{\gamma}(s, t) - \gamma(s, t) - \frac{1}{2} h_\gamma^2 \sigma_K^2 \left(\frac{\partial^2 \gamma}{\partial s^2}(s, t) + \frac{\partial^2 \gamma}{\partial t^2}(s, t) \right) + o_p(h_\gamma^2) \right] \xrightarrow{d} \mathcal{N}(0, 1),$$

where

$$\begin{aligned} \Gamma_\gamma = [1 + \mathbf{I}(\mathbf{s} = \mathbf{t})] & \left[\frac{\sum_{i=1}^n n_i(n_i - 1)v_i^2}{h_\gamma^2} \|K\|^4 \frac{V_1(s, t)}{f(s)f(t)} + \frac{\sum_{i=1}^n n_i(n_i - 1)(n_i - 2)v_i^2}{h_\gamma} \right. \\ & \times \frac{f(s)V_2(t, s) + f(t)V_2(s, t)}{f(s)f(t)} \left. \right] + \left[\sum_{i=1}^n n_i(n_i - 1)(n_i - 2)(n_i - 3)v_i^2 \right] V_3(s, t), \end{aligned}$$

and $\mathbf{I}(\cdot)$ is the indicator function.

Summary for Covariance Estimation

Unified asymptotic normality for general weight functions:

① Three partitions: non-dense, dense, and ultra-dense.

② Two special weighing schemes:

$\hat{\Sigma}_{obs}$ more efficient for non-dense data;

$\hat{\Sigma}_{sub}$ more efficient for ultra-dense data.

Summary for Covariance Estimation

Unified asymptotic normality for general weight functions:

- 1 Three partitions: non-dense, dense, and ultra-dense.
- 2 Two special weighing schemes:
 $\hat{\Sigma}_{obs}$ more efficient for non-dense data;
 $\hat{\Sigma}_{sub}$ more efficient for ultra-dense data.
- 3 Discontinuity of the asymptotic variance of the covariance estimates:

Asymptotic variance expressions are different between $s = t$ and $s \neq t$.

Discontinuity of the Asymptotic Variance

Technical Explanation:

$E[K_h(T - t)K_h(T - s)] = 0$, for $s \neq t$ when $h \rightarrow 0$ for K on an interval;

$E[K_h(T - t)K_h(T - s)] = \|K\|^2 f(t)/h + o(1/h)$, for $s = t$.

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- **Intuitive explanation?**

End of Asymptotic Theory



References for Mean and Covariance Estimation

- Yao Mueller and W. (2005, JASA)
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- Zhang and W. (2016, Ann. Stat.)
- **Additional References:**
Stainiswalis and Lee (1998, JASA),
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End of Part I

